

Amendments to the Specification:

Please replace the paragraph beginning at page 14, line 24 with the following amended paragraph:

Figure 22 shows a schematic representation of a linkage mechanism according to an embodiment of the invention exemplified by that in Figs. 1 to 3 or Figs. 13 to 15, in which the dimensions of the various components of the mechanism are indicated. The Figure also shows in phantom line a series of positions adopted by the mechanism as it rocks from one extreme position to the other. During this motion of about  $\pm 19.5$  degrees ( $38.94^\circ$  included angle) of travel of the virtual upper triangle (sides of 15mm) about the virtual pivot axis 24, the virtual pivot axis, whilst remaining on the central plane of symmetry, moves vertically by a distance of 0.3 mm. In the embodiment shown in Figure 23, where the dimensions of the individual components are slightly different, the virtual pivot axis moves vertically by a distance of 0.37 mm over an amount of travel of about  $\pm 14.5$  degrees ( $28.96^\circ$  included angle) of the upper virtual triangle (sides of 20mm). In the embodiment of Figure 22, the top arm, meaning the distance from the virtual pivot to the point of attachment of each support arm, has a length of 15 mm. In Figure 23, the top arm has a length of 20 mm. The bottom triangle determined by the main transverse link (10 mm) is the same in each of Figures 22 and 23, and is rotated through the same  $\pm 30$  degree of travel ( $60^\circ$  included angle). The upper virtual triangle in Figure 23 is referred to as "twice the size" of the lower triangle (20:10), whereas the upper virtual triangle in Figure 22 is referred to as "one-and-one-half the size" of the lower triangle (15:10).